QUICKSTART "BASIC" GUIDELINES FOR MODEL 1603 - DOWN LOOP WITH ENTRY LANE TRAFFIC ONLY

CAUTION: Installation and use of traffic control spike unit in areas that are subject to freezing weather with the Model 1603 is intended for installation only on barrier gates used for vehicles. Pedestrians must be supplied potential of snow and ice accumulation is not recommended. The unit may freeze in the up position and cause \mathbf{D} 0 R with a separate access opening. For safety and installation instructions, please refer to the Installation/owner's manual unintended injury or damage due the inability of the spikes to retract. 120 S. Glasgow Avenue Inglewood, California 90301 **Limit Magnets** have been UP Limit M~ It is recommended that the Securina **Auto Spikes** Arm in the Tunnel Plate 🖨 pre-set at the factory to rotate arm 90° "Spike" sections not exceed 9 **DOWN Position** No adjustment is necessary. Magnet feet (Three 3-Ft spike sections) Arm **DOWN**.... Spikes **UP**. **Board Adjustments** for proper operation. **Assembly** Arm UP.... Spikes DOWN. **Refer to Section 3** 🖺 3/8" x 3" See reverse side. **Auto Spike** System **Auto-Close Timer** Installation 2. OFF 3. OFF Arm mounts in the manual on the left 4. **ON** 5. OFF 6. OFF Hub for COMPLETE side of the Easily Visible Decal spike When SW1, switch 7 is turned operator. 7. Timer ON, automatic timer can be installation. SW1 set from 3.5-59 seconds to ODE BONOT INSTALL **Note:** Operator shown DOWN automatically lower arm. 2. OFF 3. OFF 4. OFF 5. OFF 6. OFF 7. OFF Limit mounted on the **LEFT** side Magnet Single Channel of traffic lane (preferred). Spike-to-Spike Connection Magnetic Note: The auto close timer Sensor CAN be used with down loops. Refer to the manual SW2 for more info. Spike Assembly 1. Snap all sections together using **Loop Detectors** socket connectors with spikes aligned with each other. Not included - Refer to the manual and Loop **Important Note:** Operator extension section's torsion shaft Information Manual (available free from **MUST** connect to operator. www.dkaccess.com) for more information Chassis Ground 🔘 📙 Note: Spike adjustment on loops and loop detectors. 2. Test spike rotation **BEFORE** may be necessary after securing tunnel plates to installation, see manual concrete with 3/8" x 3" sleeve **VAC Connection** anchors. Mounting Operator and Auto Spikes Arm **OPERATOR MUST BE PROPERLY GROUNDED!! Bracket Tip:** It is recommended that a surge suppressor 115 VAC 115 VA Vertical **HOIGS** be installed on the high voltage power lines **Chassis Ground** Neutral To #6 N.(**Inside Operator** Arm Direction -Secure the operator to the concrete Horizontal pad with the mounting flange using Bracket holes 0000 1/2" x 3" minimum sleeve anchors **▲ DANGER** Sleeve Anchor (not supplied). Important: Mount hub as **III HIGH VOLTAGE!** shown with operator in the **DOWN** position. Test hub UP 0000 Approximate position of conduit runs. and DOWN positions BEFORE installing arm. **Access** Sections **MUST** lay flat and level to operate properly! Note: "Optional" High Secure the tunnel plates Voltage Kit black and to the concrete pad using white wires connect 3/8" x 3" sleeve anchors the same as shown. (not supplied). Cut off See High Voltage Kit instruction sheet for excess threads flush with See reverse side and refer Depth of concrete under the operator more information to Installation/Owner's Conduit top of nut on all ramps. is determined by soil conditions and manual for other access **115 VAC** local building codes Conduit control device connections Copyright 2025 DoorKing®, Inc. All rights reserved.

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CKSTART "BASIC" GUIDELINES FOR MODEL 1603 - DIP-SWITCH AND WIRING REFERENCE

Model 1603 is intended for installation only on barrier gates used for vehicles.

Pedestrians must be supplied with a separate access opening. For safety and installation instructions, please refer to the owner's manual.

SW 1 DIP-Switches

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SW 1

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SW 2

Switch	Function	Setting	Description
1	Down Active when arm is full up.	OFF	Activation and then deactivation of the down loop or down / reverse input will cause the arm to rotate down ONLY if the deactivation occurred after the arm reached the FULL UP position.
	Down Active when arm is moving up or is up.	ON	Activation and then deactivation of the down loop or down / reverse input will cause the arm to rotate down AFTER reaching the FULL UP position regardless of when the deactivation occurred.
2	Self-Test	0FF	Normal setting. Self-test is turned off.
		ON	Run self-test.
	Gear Box Travel	0FF	Normal setting. Operator uses 360° of gearbox. Extends wear life of gearbox.
3		ON	Operator uses 180° of gearbox.
	Down / Reverse Loop and Input	OFF	Down / Reverse loop and input will function as a REVERSE loop and REVERSE input.
4		ON	Normal setting. Down / Reverse loop and input will function as a down input and cause the arm to rotate down upon deactivation of the input. See SW 1, switch 1 for additional information.
5	Relay 1 Activation	OFF	Normal setting. Relay activates when the DOWN loop detector (DoorKing plug-in detector only) senses a vehicle presence.
		ON	Relay activates when the UP loop detector (DoorKing plug-in detector only) senses a vehicle presence.
6	Up Input Function	OFF	Up Input will raise arm and/or reset the down timer. Input will not lower the arm.
U		ON	Up Input will raise arm if it is down, or will lower arm if it is up.
	Timer	OFF	Timer to lower arm is OFF.
7		ON	Timer to lower arm is ON. Set from 3.5 to 59 seconds for close time delay. Timer can be used as a secondary closing command for a down loop. Timer countdown starts when arm has fully raised. Down loop activation will cancel timer and lower arm OR arm will lower when timer has timed out.
8	Up Loop Port Input	OFF	Output of the loop detector plugged into the UP loop port is switched to terminal 7 for connection to other input terminals.
0		ON	Normal setting. Output of the loop detector plugged into the UP loop port will raise arm when activated.

SW 2 DIP-Switches

Function

Setting

Switch

Note: After a DIP-switch setting is changed, power must be turned OFF and then turned back on for the new setting to take affect.

Description

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	1	Model 1603	OFF	Switch must be OFF for model 1603 barrier gate operator.
	2	Multiple Input Memory ON/OFF Switch	OFF	Normal setting. Operator will respond to a single UP command, then require a DOWN command. Operator will not accept multiple Up commands. Operator will not accept the next UP command until the previous DOWN command is in progress.
			ON	Turns ON the multiple input memory option 1 or 2 (See switch 3). SW 1, switch 4 must also be on.
	3	Multiple Input Memory Options (SW2, Switch 2 must be ON) (SW1, Switch 4 must be ON)	Option 1 (OFF Position)	Override a DOWN command — When the arm is in the up position for a vehicle passing through and the next vehicle's UP command is received, the operator will hold the arm up and wait for the next vehicle to clear the down loop before lowering the arm. The operator will not count multiple UP commands. Distance between access control device and barrier operator is a factor when using this option. Remote transmitters recommended for this option. See Installation/Owner's manual for more information.
			Option 2 (ON Position)	Override Mulitipe DOWN commands – The operator will count multiple UP commands received during an UP command and require a matching number of DOWN commands before lowering the arm. Distance between access control device and barrier operator is a factor when using this option. Remote transmitters NOT recommended for this option. See Installation/Owner's manual for more information.
	4	Stop Arm Function	OFF	Normal setting. Arm will NOT stop DURING the down cycle.
			ON	Stop Arm Function – Arm will stop DURING the down cycle if a vehicle activates the down loop. An UP command will raise the arm, or the arm will continue down AFTER the down loop is cleared.
	5	Reverse Delay	OFF	Arm reversal is delayed approximately .5 seconds when a reverse input from terminal 9 is received during the down cycle. (eg. non-contact sensor beam is blocked). Limited application use.
			ON	Normal setting. Instant Reverse – Arm reversal is delayed approximately .1 second when a reverse input from terminal 9 is received during the down cycle. (eg. non-contact sensor beam is blocked)
ı	6	Arm Rotation Direction	0FF	Normal setting. Leave in OFF position.
	7	Warn Before Operate Beeper	OFF	Beeper will beep 2 times before lowering arm ONLY when the TIMER times out. If using a down loop, when it gets activated, it will cancel the timer and lower arm WITHOUT beeping .
			ON	Beeper will beep 2 times before lowering arm EVERYTIME .
	8	Spare	OFF	Normal setting. Leave in OFF position.



120 S. Glasgow Avenue

